

**NEW**

**Brushless DC-Servomotors**  
4 Pole Technology

165 mNm  
150 W

**Series 3274 ... BP4**

Values at 22°C and nominal voltage		3274 G	024 BP4
1	Nominal voltage	$U_N$	24 V
2	Terminal resistance, phase-phase	$R$	0,25 $\Omega$
3	Efficiency, max.	$\eta_{max}$	89 %
4	No-load speed	$n_0$	8 700 min <sup>-1</sup>
5	No-load current, typ. (with shaft $\varnothing$ 5 mm)	$I_0$	0,384 A
6	Stall torque	$M_H$	2 697 mNm
7	Friction torque, static	$C_0$	2,9 mNm
8	Friction torque, dynamic	$C_V$	$8,2 \cdot 10^{-4}$ mNm/min <sup>-1</sup>
9	Speed constant	$k_n$	336 min <sup>-1</sup> /V
10	Back-EMF constant	$k_E$	2,97 mV/min <sup>-1</sup>
11	Torque constant	$k_M$	28,4 mNm/A
12	Current constant	$k_I$	0,035 A/mNm
13	Slope of n-M curve	$\Delta n / \Delta M$	3 min <sup>-1</sup> /mNm
14	Terminal inductance, phase-phase	$L$	60 $\mu$ H
15	Mechanical time constant	$\tau_m$	1,5 ms
16	Rotor inertia	$J$	48 gcm <sup>2</sup>
17	Angular acceleration	$\alpha_{max}$	$\cdot 10^3$ rad/s <sup>2</sup>
18	Thermal resistance	$R_{th1} / R_{th2}$	0,7 / 8 K/W
19	Thermal time constant	$\tau_{w1} / \tau_{w2}$	14 / 965 s
20	Operating temperature range:		
	– motor	-40 ... +125	°C
	– winding, max. permissible	+150	°C
21	Shaft bearings	ball bearings, preloaded	
22	Shaft load max.:		
	– with shaft diameter	5	mm
	– radial at 3 000 min <sup>-1</sup> (5 mm from mounting flange)	50	N
	– axial at 3 000 min <sup>-1</sup> (push only)	5	N
	– axial at standstill (push only)	50	N
23	Shaft play:		
	– radial $\leq$	0,015	mm
	– axial $=$	0	mm
24	Housing material	stainless steel	
25	Mass	320	g
26	Direction of rotation	electronically reversible	
27	Speed up to	$n_{max}$	16 000 min <sup>-1</sup>
28	Number of pole pairs	2	
29	Hall sensors	digital	
30	Magnet material	NdFeB	
<b>Rated values for continuous operation</b>			
31	Rated torque	$M_N$	111,2 mNm
32	Rated current (thermal limit)	$I_N$	4,8 A
33	Rated speed	$n_N$	8 490 min <sup>-1</sup>

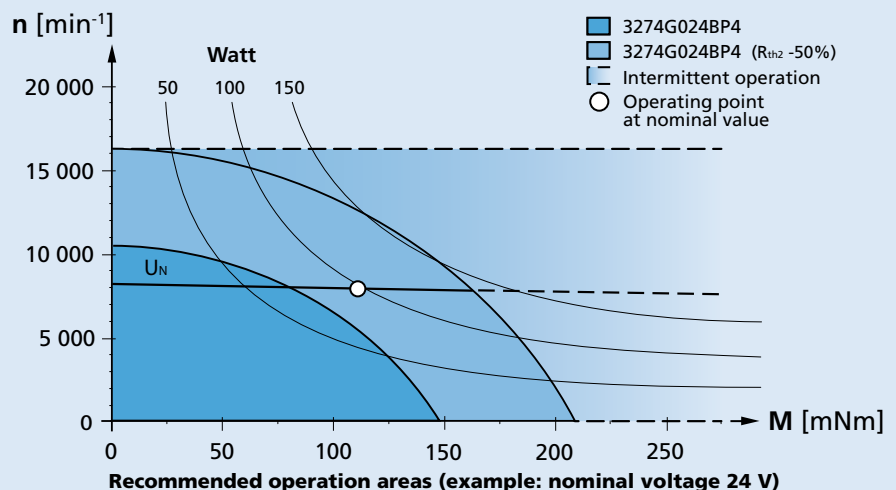
**Note:** Rated values are calculated with nominal voltage and at a 22°C ambient temperature. The  $R_{th2}$  value has been reduced by 25%.

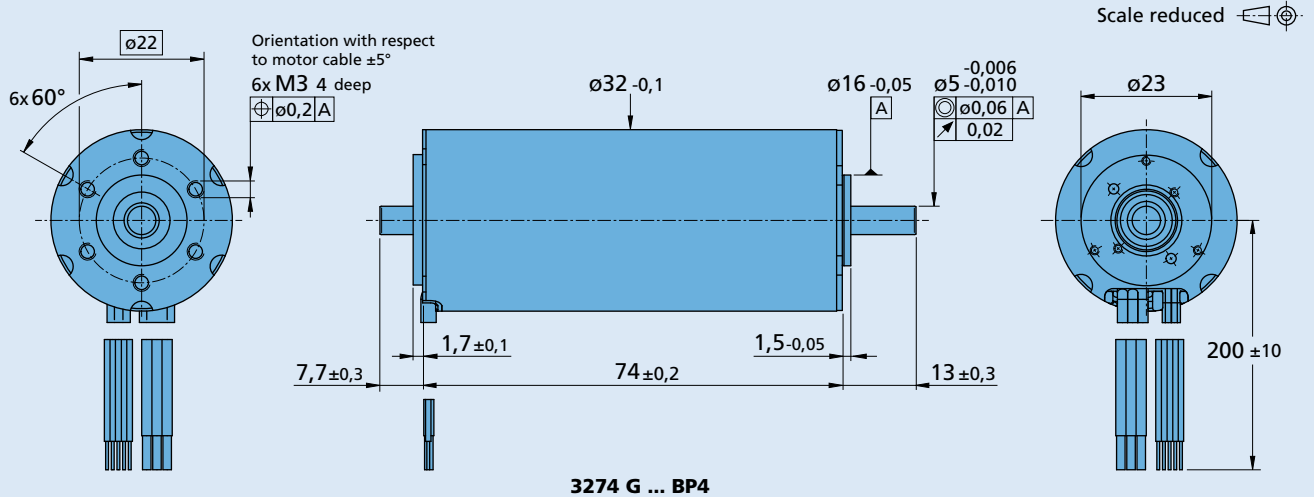
**Note:**

The diagram indicates the recommended speed in relation to the available torque at the output shaft for a given ambient temperature of 22°C.

The diagram shows the motor in a completely insulated as well as thermally coupled condition ( $R_{th2}$  50% reduced).

The nominal voltage ( $U_N$ ) curve shows the operating point at nominal voltage in the insulated and thermally coupled condition. Any points of operation above the curve at nominal voltage will require a higher operating voltage. Any points below the nominal voltage curve will require less voltage.



**Dimensional drawing**

**Option, cable and connection information**

 Example product designation: **3274G024BP4-3692**

Option	Type	Description	Connection	
			Function	Colour
Y158	Shaft end	Motor without second shaft end	Phase C	yellow
3692	Controller combination	Analog Hall sensors for combination with Motion Controller MCBL	Phase B	orange
			Phase A	brown
			GND	black
			U <sub>DD</sub> (+5V)	red
			Hall sensor C	grey
			Hall sensor B	blue
			Hall sensor A	green
			<b>Standard cable</b>	
			3 single wires, material FEP, AWG 18, Phase A/B/C	
			5 single wires, material PTFE, AWG 26, Hall A/B/C, U <sub>DD</sub> , GND	

**Product Combination**

Precision Gearheads / Lead Screws	Encoders	Drive Electronics	Cables / Accessories
32A 32ALN 32/3 32/3 S 38A 38/1 38/1 S 38/2 38/2 S	HEDS 5500 HEDM 5500 IE3-1024 IE3-1024 L HEDS 5540 HEDL 5540	SC 5008 MCBL 3006	6501.00134 Braking chopper BC5004